Arduino - Overview

Arduino is a prototype platform (open-source) based on an easy-to-use hardware and software. It consists of a circuit board, which can be programmed (referred to as a microcontroller) and a ready-made software called Arduino IDE (Integrated Development Environment), which is used to write and upload the computer code to the physical board.

The key features are -

- Arduino boards are able to read analog or digital input signals from different sensors and turn it into an output such as activating a motor, turning LED on/off, connect to the cloud and many other actions.
- You can control your board functions by sending a set of instructions to the microcontroller on the board via Arduino IDE (referred to as uploading software).
- Unlike most previous programmable circuit boards, Arduino does not need an extra piece of hardware (called a programmer) in order to load a new code onto the board. You can simply use a USB cable.
- Additionally, the Arduino IDE uses a simplified version of C++, making it easier to learn to program.
- Finally, Arduino provides a standard form factor that breaks the functions of the microcontroller into a more accessible package.





Board Types

Various kinds of Arduino boards are available depending on different microcontrollers used. However, all Arduino boards have one thing in common: they are programed through the Arduino IDE.

The differences are based on the number of inputs and outputs (the number of sensors, LEDs, and buttons you can use on a single board), speed, operating voltage, form factor etc. Some boards are designed to be embedded and have no programming interface (hardware), which you would need to buy separately. Some can run directly from a 3.7V battery, others need at least 5V.

Here is a list of different Arduino boards available.

Board Name	Operating Volt	Clock Speed	Digital i/o	Analog Inputs	PWM	UART	Programming Interface
Arduino Uno R3	5V	16MHz	14	6	6	1	USB via ATMega16U2
Arduino Uno R3 SMD	5V	16MHz	14	6	6	1	USB via ATMega16U2
Red Board	5V	16MHz	14	6	6	1	USB via FTDI
Arduino Pro 3.3v/8 MHz	3.3V	8MHz	14	6	6	1	FTDI-Compatible Header
Arduino Pro 5V/16MHz	5V	16MHz	14	6	6	1	FTDI-Compatible Header
Arduino mini 05	5V	16MHz	14	8	6	1	FTDI-Compatible Header
Arduino Pro mini 3.3v/8mhz	3.3V	8MHz	14	8	6	1	FTDI-Compatible Header
Arduino Pro mini 5v/16mhz	5V	16MHz	14	8	6	1	FTDI-Compatible Header

Arduino boards based on ATMEGA328 microcontroller

Arduino Ethernet	5V	16MHz	14	6	6	1	FTDI-Compatible Header
Arduino Fio	3.3V	8MHz	14	8	6	1	FTDI-Compatible Header
LilyPad Arduino 328 main board	3.3V	8MHz	14	6	6	1	FTDI-Compatible Header
LilyPad Arduino simple board	3.3V	8MHz	9	4	5	0	FTDI-Compatible Header

Arduino boards based on ATMEGA32u4 microcontroller

Board Name	Operating Volt	Clock Speed	Digital i/o	Analog Inputs	PWM	UART	Programming Interface
Arduino Leonardo	5V	16MHz	20	12	7	1	Native USB
Pro micro 5V/16MHz	5V	16MHz	14	6	6	1	Native USB
Pro micro 3.3V/8MHz	5V	16MHz	14	6	6	1	Native USB
LilyPad Arduino USB	3.3V	8MHz	14	6	6	1	Native USB

Arduino boards based on ATMEGA2560 microcontroller

Board Name	Operating Volt	Clock Speed	Digital i/o	Analog Inputs	PWM	UART	Programming Interface
Arduino Mega 2560 R3	5V	16MHz	54	16	14	4	USB via ATMega16U2B

Mega Pro 3.3V	3.3V	8MHz	54	16	14	4	FTDI-Compatible Header
Mega Pro 5V	5V	16MHz	54	16	14	4	FTDI-Compatible Header
Mega Pro Mini 3.3V	3.3V	8MHz	54	16	14	4	FTDI-Compatible Header

Arduino boards based on AT91SAM3X8E microcontroller

Board Name	Operating Volt	Clock Speed	Digital i/o	Analog Inputs	PWM	UART	Programming Interface
Arduino Mega 2560 R3	3.3V	84MHz	54	12	12	4	USB native

Arduino - Board Description

we will learn about the different components on the Arduino board. We will study the Arduino UNO board because it is the most popular board in the Arduino board family. In addition, it is the best board to get started with electronics and coding. Some boards look a bit different from the one given below, but most Arduinos have majority of these components in common.



Arduino boards can be powered directly from the AC mains power supply by connecting it to the Barrel Jack (2).



Voltage Regulator

The function of the voltage regulator is to control the voltage given to the Arduino board and stabilize the DC voltages used by the processor and other elements.

4	Crystal Oscillator The crystal oscillator helps Arduino in dealing with time issues. How does Arduino calculate time? The answer is, by using the crystal oscillator. The number printed on top of the Arduino crystal is 16.000H9H. It tells us that the frequency is 16,000,000 Hertz or 16 MHz.
5,17	Arduino Reset You can reset your Arduino board, i.e., start your program from the beginning. You can reset the UNO board in two ways. First, by using the reset button (17) on the board. Second, you can connect an external reset button to the Arduino pin labelled RESET (5).
6,7 8,9	 Pins (3.3, 5, GND, Vin) 3.3V (6) - Supply 3.3 output volt 5V (7) - Supply 5 output volt Most of the components used with Arduino board works fine with 3.3 volt and 5 volt. GND (8)(Ground) - There are several GND pins on the Arduino, any of which can be used to ground your circuit. Vin (9) - This pin also can be used to power the Arduino board from an external power source, like AC mains power supply.
10	Analog pins The Arduino UNO board has six analog input pins A0 through A5. These pins can read the signal from an analog sensor like the humidity sensor or temperature sensor and convert it into a digital value that can be read by the microprocessor.
11	Main microcontroller Each Arduino board has its own microcontroller (11). You can assume it as the brain of your board. The main IC (integrated circuit) on the Arduino is slightly different from board to board. The microcontrollers are usually of the ATMEL Company. You must know what IC your board has before loading up a new program from the Arduino IDE. This information is available on the top of the IC. For more details about the IC construction and functions, you can refer to the data sheet.
12	ICSP pin Mostly, ICSP (12) is an AVR, a tiny programming header for the Arduino consisting of MOSI, MISO, SCK, RESET, VCC, and GND. It is often referred to as an SPI (Serial Peripheral Interface), which could be considered as an "expansion" of the

	output. Actually, you are slaving the output device to the master of the SPI bus.
13	Power LED indicator This LED should light up when you plug your Arduino into a power source to indicate that your board is powered up correctly. If this light does not turn on, then there is something wrong with the connection.
14	TX and RX LEDs On your board, you will find two labels: TX (transmit) and RX (receive). They appear in two places on the Arduino UNO board. First, at the digital pins 0 and 1, to indicate the pins responsible for serial communication. Second, the TX and RX led (13). The TX led flashes with different speed while sending the serial data. The speed of flashing depends on the baud rate used by the board. RX flashes during the receiving process.
15	Digital I/O The Arduino UNO board has 14 digital I/O pins (15) (of which 6 provide PWM (Pulse Width Modulation) output. These pins can be configured to work as input digital pins to read logic values (0 or 1) or as digital output pins to drive different modules like LEDs, relays, etc. The pins labeled "~" can be used to generate PWM.
16	AREF AREF stands for Analog Reference. It is sometimes, used to set an external reference voltage (between 0 and 5 Volts) as the upper limit for the analog input pins.

Arduino - Installation

In this section, how to set up the Arduino IDE on our computer and prepare the board to receive the program via USB cable.

Step 1 – First you must have your Arduino board (you can choose your favorite board) and a USB cable. In case you use Arduino UNO, Arduino Duemilanove, Nano, Arduino Mega 2560, or Diecimila, you will need a standard USB cable (A plug to B plug), the kind you would connect to a USB printer as shown in the following image.



In case you use Arduino Nano, you will need an A to Mini-B cable instead as shown in the following image.



Step 2 – Download Arduino IDE Software.

You can get different versions of Arduino IDE from the Download page on the Arduino Official website. You must select your software, which is compatible with your operating system (Windows, IOS, or Linux). After your file download is complete, unzip the file.

Opening arduino-nigh	ntly-windows.zip	X
You have chosen to	open:	
🖀 arduino-night	ly-windows.zip	
which is: Winf	AR ZIP archive (148 MB)	
from: https://d	downloads.arduino.cc	
What should Firefo	x do with this file?	
Open with	WinRAR archiver (default)	-
Save File]
🔲 Do this <u>a</u> uto	matically for files like this from now on.	
	OK Canc	el

Step 3 – Power up your board.

The Arduino Uno, Mega, Duemilanove and Arduino Nano automatically draw power from either, the USB connection to the computer or an external power supply. If you are using an Arduino Diecimila, you have to make sure that the board is configured to draw power from the USB connection. The power source is selected with a jumper, a small piece of plastic that fits onto two of the three pins between the USB and power jacks. Check that it is on the two pins closest to the USB port.

Connect the Arduino board to your computer using the USB cable. The green power LED (labeled PWR) should glow.

Step 4 – Launch Arduino IDE.

After your Arduino IDE software is downloaded, you need to unzip the folder. Inside the folder, you can find the application icon with an infinity label (application.exe). Double-click the icon to start the IDE.

Organize	Disk (C:) Program Files Arduino Share with Burn New folder			
🔆 Favorites	Name	Date modified	Туре	Size
E Desktop	🕌 drivers	9/27/2015 1:24 PM	File folder	
Downloads	acamples	9/27/2015 1:31 PM	File folder	
3 Recent Places	👪 hardware	9/27/2015 1:31 PM	File folder	
	🗼 java	9/27/2015 1:25 PM	File folder	
🛜 Libraries	\rm lib	9/27/2015 1:32 PM	File folder	
Documents	🎉 libraries	11/19/2015 5:59 PM	File folder	
J Music	\mu reference	9/27/2015 1:25 PM	File folder	
E Pictures	\rm tools	9/27/2015 1:25 PM	File folder	
📑 Videos	💿 arduino 🥌	9/16/2014 3:46 PM	Application	844 KB
	💿 arduino_debug	9/16/2014 3:46 PM	Application	383 KB
Somputer	S cygiconv-2.dll	9/16/2014 3:46 PM	Application extens	947 KB
🚢 Local Disk (C:)	🚳 cygwin1.dll	9/16/2014 3:46 PM	Application extens	1,829 KB
MTC MASTER (D:)	ibusb0.dll	9/16/2014 3:46 PM	Application extens	43 KB
INFORMATION TECHNOLOG	revisions	9/16/2014 3:46 PM	Text Document	39 KB
	ixtoSerial.dll	9/16/2014 3:46 PM	Application extens	76 KB
On Matural	😰 uninstall	9/27/2015 1:26 PM	Application	402 KB

Step 5 – Open your first project.

Once the software starts, you have two options -

- Create a new project.
- Open an existing project example.

To create a new project, select File \rightarrow **New**.

sketch_nov29a Arduino 1.0.6				sketch_nov29a Arduino 1.0.6	- C ×
New	Ctrl-N	173			
Open	Ctrl+O	Led.		OO B B M	2
Sketchbook				sketch_nov29a	
Examples				0	
Close	Ctrl+W				
Save	Ctrl+S				
Save As	Ctrl+Shift+S				
Upload	Ctrl+U		11.0		
Upload Using Programmer	Ctrl+Shift+U				
Page Setup	Ctrl+Shift+P				
Print	Ctrl+P				
Preferences	Ctrl+Comma				
Quit	Ctrl+Q				
1	Ardu	ine Une en COM18		1	Arduine Une on COM18

To open an existing project example, select File \rightarrow Example \rightarrow Basics \rightarrow Blink.



Here, we are selecting just one of the examples with the name **Blink**. It turns the LED on and off with some time delay. You can select any other example from the list.

Step 6 – Select your Arduino board.

To avoid any error while uploading your program to the board, you must select the correct Arduino board name, which matches with the board connected to your computer.

			Teensy 3.2 / 3.1
			Teensy 3.0
			TeensyLC
• • • • • • • • • • • • • • • • • • •			Teensy 2.0
Blink Arduno 1.0.6			Teensy++ 2.0
File Edit Sketch Tools Help		•	Arduino Uno
Auto Format	Ctrl+T		Arduino Duemilanove w/ ATmega328
Archive Sketch			Arduino Diecimila or Duemilanove w/ ATmega168
Fix Encoding & Reload			Arduino Nano w/ ATmaga228
Serial Monitor	Ctrl+Shift+M		Arduino Nano w/ Armega168
Board: "Arduino Uno"			Arduino Mano 2560 er Mano ADK
Serial Port	,		Arduino Mega 2000 or Mega ADK
LISB Type			Arduino Mega (A I mega1280)
CPUISpeed	(Arduno Leonardo
CPO speed	ĺ.		Arduino Esplora
Keyboard Layout	/		Arduino Micro
Programmer	•		Arduino Mini w/ ATmega328
Burn Bootloader			Arduino Mini w/ ATmega168
			Arduino Ethernet
			Arduino Fio
			Arduino BT w/ ATmega328
			Arduino BT w/ ATmega168
			LilyPad Arduino USB
			LilyPad Arduino w/ ATmega328
4			LilyPad Arduino w/ ATmega168
			Arduino Pro or Pro Mini (5V, 16 MHz) w/ ATmega328
			Arduino Pro or Pro Mini (5V, 16 MHz) w/ ATmega168
			Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ ATmega328
			Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ ATmega168
			Arduino NG or older w/ ATmega168
1			Arduino NG or older w/ ATmega8
			Arduino Robot Control
			Arduino Robot Motor

Go to Tools \rightarrow Board and select your board.

Here, we have selected Arduino Uno board according to our tutorial, but you must select the name matching the board that you are using.

Step 7 – Select your serial port.

Select the serial device of the Arduino board. Go to **Tools** \rightarrow **Serial Port** menu. This is likely to be COM3 or higher (COM1 and COM2 are usually reserved for hardware serial ports). To find out, you can disconnect your Arduino board and re-open the menu, the entry that disappears should be of the Arduino board. Reconnect the board and select that serial port.

Silink Arduing File Edit Sketch	1.0.6 Tools Help	9. 9.			
OOEI. Blink§	Auto Format Archive Sketch Fix Encoding & Reload Serial Monitor	Ctrl+T Ctrl+Shift+M			
	Board: "Arduino Uno"	•			
	Serial Port	•	COM1		
	CPU Speed	•	COM2 COM3		
	Keyboard Layout	F			
	Programmer Burn Bootloader	•			
4				*	
1			Arduino Uno on	COM16	

Step 8 – Upload the program to your board.

Before explaining how we can upload our program to the board, we must demonstrate the function of each symbol appearing in the Arduino IDE toolbar.



- A Used to check if there is any compilation error.
- **B** Used to upload a program to the Arduino board.
- **C** Shortcut used to create a new sketch.
- **D** Used to directly open one of the example sketch.
- E Used to save your sketch.

F – Serial monitor used to receive serial data from the board and send the serial data to the board.

Now, simply click the "Upload" button in the environment. Wait a few seconds; you will see the RX and TX LEDs on the board, flashing. If the upload is successful, the message "Done uploading" will appear in the status bar.

Note – If you have an Arduino Mini, NG, or other board, you need to press the reset button physically on the board, immediately before clicking the upload button on the Arduino Software.

Arduino - Program Structure

we will study in depth, the Arduino program structure and we will learn more new terminologies used in the Arduino world. The Arduino software is open-source. The source code for the Java environment is released under the GPL and the C/C++ microcontroller libraries are under the LGPL.

Sketch – The first new terminology is the Arduino program called "sketch".

Structure

Arduino programs can be divided in three main parts: **Structure, Values** (variables and constants), and **Functions**. we will learn about the Arduino software program, step by step, and how we can write the program without any syntax or compilation error.

Let us start with the Structure. Software structure consist of two main functions -

- Setup() function
- Loop() function



Void setup () {

}

- **PURPOSE** The **setup()** function is called when a sketch starts. Use it to initialize the variables, pin modes, start using libraries, etc. The setup function will only run once, after each power up or reset of the Arduino board.
- INPUT -

- OUTPUT -
- RETURN -

```
Void Loop ( ) {
```

}

- **PURPOSE** After creating a **setup()** function, which initializes and sets the initial values, the **loop()** function does precisely what its name suggests, and loops consecutively, allowing your program to change and respond. Use it to actively control the Arduino board.
- INPUT -
- OUTPUT -
- RETURN -

Arduino - Data Types

Data types in C refers to an extensive system used for declaring variables or functions of different types. The type of a variable determines how much space it occupies in the storage and how the bit pattern stored is interpreted.

The following table provides all the data types that you will use during Arduino programming.

void	Boolean	char	Unsigned	byte	int	Unsigned int	word
			char				
long	Unsigned	short	float	double	array	String-char	String-
	long					array	object

void

The void keyword is used only in function declarations. It indicates that the function is expected to return no information to the function from which it was called.

Example

Void Loop () {

```
// rest of the code
}
```

Boolean

A Boolean holds one of two values, true or false. Each Boolean variable occupies one byte of memory.

Example

```
boolean val = false ; // declaration of variable with type boolean
and initialize it with false
boolean state = true ; // declaration of variable with type boolean
and initialize it with true
```

Char

A data type that takes up one byte of memory that stores a character value. Character literals are written in single quotes like this: 'A' and for multiple characters, strings use double quotes: "ABC".

However, characters are stored as numbers. You can see the specific encoding in the ASCII chart. This means that it is possible to do arithmetic operations on characters, in which the ASCII value of the character is used. For example, 'A' + 1 has the value 66, since the ASCII value of the capital letter A is 65.

Example

```
Char chr_a = `a' ;//declaration of variable with type char and initialize it with character a
Char chr_c = 97 ;//declaration of variable with type char and initialize it with character 97
```

unsigned char

Unsigned char is an unsigned data type that occupies one byte of memory. The unsigned char data type encodes numbers from 0 to 255.

Example

```
Unsigned Char chr_y = 121 ; // declaration of variable with type Unsigned char and initialize it with character y
```

byte

A byte stores an 8-bit unsigned number, from 0 to 255.

Example

byte m = 25 ;//declaration of variable with type byte and initialize it with 25 $\,$

int

Integers are the primary data-type for number storage. int stores a 16-bit (2-byte) value. This yields a range of -32,768 to 32,767 (minimum value of -2^{15} and a maximum value of $(2^{15}) - 1$).

The **int** size varies from board to board. On the Arduino Due, for example, an **int** stores a 32-bit (4-byte) value. This yields a range of -2,147,483,648 to 2,147,483,647 (minimum value of -2^31 and a maximum value of (2^31) - 1).

Example

```
int counter = 32 ;// declaration of variable with type int and initialize it with 32
```

Unsigned int

Unsigned ints (unsigned integers) are the same as int in the way that they store a 2 byte value. Instead of storing negative numbers, however, they only store positive values, yielding a useful range of 0 to 65,535 (2^16) - 1). The Due stores a 4 byte (32-bit) value, ranging from 0 to 4,294,967,295 (2^32 - 1).

Example

```
Unsigned int counter = 60 ; // declaration of variable with
   type unsigned int and initialize it with 60
```

Word

On the Uno and other ATMEGA based boards, a word stores a 16-bit unsigned number. On the Due and Zero, it stores a 32-bit unsigned number.

Example

```
word w = 1000 ;//declaration of variable with type word and initialize it with 1000
```

Long

Long variables are extended size variables for number storage, and store 32 bits (4 bytes), from -2,147,483,648 to 2,147,483,647.

Example

```
Long velocity = 102346;//declaration of variable with type Long and initialize it with 102346
```

unsigned long

Unsigned long variables are extended size variables for number storage and store 32 bits (4 bytes). Unlike standard longs, unsigned longs will not store negative numbers, making their range from 0 to 4,294,967,295 (2^32 - 1).

Example

```
Unsigned Long velocity = 101006 ;// declaration of variable with type Unsigned Long and initialize it with 101006
```

short

A short is a 16-bit data-type. On all Arduinos (ATMega and ARM based), a short stores a 16-bit (2-byte) value. This yields a range of -32,768 to 32,767 (minimum value of - 2^15 and a maximum value of (2^15) - 1).

Example

```
short val = 13 ;//declaration of variable with type short and initialize it with 13 \,
```

float

Data type for floating-point number is a number that has a decimal point. Floating-point numbers are often used to approximate the analog and continuous values because they have greater resolution than integers.

Floating-point numbers can be as large as 3.4028235E+38 and as low as - 3.4028235E+38. They are stored as 32 bits (4 bytes) of information.

Example

```
float num = 1.352;//declaration of variable with type float and initialize it with 1.352
```

double

On the Uno and other ATMEGA based boards, Double precision floating-point number occupies four bytes. That is, the double implementation is exactly the same as the float, with no gain in precision. On the Arduino Due, doubles have 8-byte (64 bit) precision.

Arduino - Variables & Constants

Before we start explaining the variable types, a very important subject we need to make sure, you fully understand is called the **variable scope**.

What is Variable Scope?

Variables in C programming language, which Arduino uses, have a property called scope. A scope is a region of the program and there are three places where variables can be declared. They are –

- Inside a function or a block, which is called **local variables**.
- In the definition of function parameters, which is called **formal parameters**.
- Outside of all functions, which is called **global variables**.

Local Variables

Variables that are declared inside a function or block are local variables. They can be used only by the statements that are inside that function or block of code. Local variables are not known to function outside their own. Following is the example using local variables –

```
Void setup () {
    int x , y ;
    int z ; Local variable declaration
    x = 0;
    y = 0; actual initialization
    z = 10;
}
```

Global Variables

Global variables are defined outside of all the functions, usually at the top of the program. The global variables will hold their value throughout the life-time of your program.

A global variable can be accessed by any function. That is, a global variable is available for use throughout your entire program after its declaration.

The following example uses global and local variables -

```
Int T , S ;
float c = 0 ; Global variable declaration
Void setup () {
    int x , y ;
    int z ; Local variable declaration
    x = 0;
    y = 0; actual initialization
    z = 10;
}
```